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## HPC — Homework 1

(A) A matrix  $A \in \mathbb{R}^{n \times n}$  is said to be symmetric and positive definite if  $A^T = A$  and  $x^T A x > 0$  for any nonzero vector  $x \in \mathbb{R}^n$ .

If A is SPD, then all eigenvalues of A are positive. Suppose v is an eigenvector.

$$v^T A v = v^T \lambda v = v^T v \lambda = ||v||^2 \lambda > 0 \implies \lambda > 0$$

(B) First note that since Ax = b,

$$J(x) = \frac{1}{2}x^{T}Ax - b^{T}x = \frac{1}{2}x^{T}Ax - x^{T}Ax = -\frac{1}{2}x^{T}Ax.$$
 (1)

For any vector  $y \in \mathbb{R}^n$ ,

$$J(y) = \frac{1}{2}y^{T}Ay - b^{T}y$$
  

$$= \frac{1}{2}y^{T}Ay - x^{T}Ay$$
  

$$= \left(\frac{1}{2}y^{T}Ay - x^{T}Ay + \frac{1}{2}x^{T}Ax\right) - \frac{1}{2}x^{T}Ax$$
  
(by (1)) 
$$= \left(\frac{1}{2}y^{T}Ay - x^{T}Ay + \frac{1}{2}x^{T}Ax\right) + J(x)$$
  
(by symmetry of A) 
$$= \frac{1}{2}(x - y)^{T}A(x - y) + J(x)$$
  

$$\ge J(x),$$

where the last inequality is due to the positive definiteness of A, and equality holds if and only if y = x. In other words, J(y) > J(x) for all  $y \neq x$ . Hence x is the unique global minimizer of J.

(C) Note that for any fixed vectors x and d,  $\alpha^* := \frac{(b-Ax)^T d}{d^T A d}$  is the unique critical point of the

function  $f(\alpha) := J(x + \alpha d)$ . First, let's see what exactly  $f(\alpha)$  is:

$$f(\alpha) = \frac{1}{2}(x + \alpha d)^T A(x + \alpha d) - b^T (x + \alpha d)$$
$$= \frac{1}{2}(x^T A x + 2\alpha x^T A d + \alpha^2 d^T A d) - b^T x - \alpha b^T d$$
$$= \left(\frac{1}{2}x^T A x - b^T x\right) + \alpha \left(x^T A d - b^T d\right) + \frac{1}{2}\alpha^2 d^T A d$$

From this, we see that

$$0 = f'(\alpha) = x^T A d - b^T d + \alpha d^T A d$$

if and only if

$$\alpha = \frac{b^T d - x^T A d}{d^T A d} = \frac{(b - Ax)^T d}{d^T A d}.$$

This shows that  $\alpha^* = \frac{(b-Ax)^T d}{d^T A d}$  is the unique critical point of f. Then we show that  $\alpha^*$  is a minimizer via the second derivative test: indeed,

$$f''(\alpha) = d^T A d > 0$$

for any  $\alpha$ , since A is SPD and  $d \neq 0$ .

In conclusion, by definition of  $r^n$ , we have that  $\arg \min_{\alpha} J(x^n + \alpha d^n) = \frac{r^n \cdot d^n}{d^n \cdot A d^n}$ .

(D) Recall (from Calculus 3) that the *gradient* of a function  $g : \mathbb{R}^n \to \mathbb{R}$  at a point  $x \in \mathbb{R}^n$ , if exists, is the unique vector v that satisfies

$$g(x+d) = g(x) + v^T d + o(||d||), \quad \forall d \in \mathbb{R}^n.$$

To compute  $\nabla J(x)$ , fix any vector  $d \in \mathbb{R}^n$ , and compute the first order approximation of J(x+d) as follows:

$$J(x+d) = \frac{1}{2}(x+d)^{T}A(x+d) - b^{T}(x+d)$$
  
=  $\frac{1}{2}(x^{T}Ax + 2x^{T}Ad + d^{T}Ad) - b^{T}x - b^{T}d$   
=  $\frac{1}{2}x^{T}Ax - b^{T}x + (A^{T}x - b)^{T}d + \frac{1}{2}d^{T}Ad$   
=  $J(x) + (Ax - b)^{T}d + o(||d||).$ 

Here we have that  $d^T A d = o(||d||)$  because

$$0 \leq \frac{d^{T}Ad}{\|d\|} \leq \|d\| \left\| A \frac{d}{\|d\|} \right\| \leq \|d\| \cdot (\text{maximum eigenvalue of } A) \to 0 \qquad \text{as } \|d\| \searrow 0.$$

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Hence  $\nabla J(x) = Ax - b = -r(x)$ .

Submitted by Sergey Voronin on December 7, 2016.

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